

In the Claims:

1. (original) A method for assisting the driver of a vehicle
(10) when performing a driving maneuver, a reference
trajectory (16) corresponding to the driving maneuver being
determined, along which the vehicle (19) is to be moved,
and the steering wheel position to be set in each case and
controlling the vehicle (10) along the reference trajectory
(16, 19) being indicated to the driver during the driving
maneuver, characterized in that, in the event of a steering
angle deviation (d_{lw}) between the actual steering angle
(δ_{act}) actually set by the driver and the desired steering
angle (δ_{des}) corresponding to the requested steering wheel
position, the vehicle longitudinal speed (v) is influenced
independently of the driver.

1 2. (original) The method as claimed in claim 1, characterized
2 in that the influence on the vehicle speed is dependent on
3 the magnitude of the steering angle deviation (d_{lw}).

Claims 3 to 14 (canceled).

[REMARKS FOLLOW ON NEXT PAGE]